



# **Floating Point Inverse Square Root (ALTFP\_INV\_SQRT)**

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## **Megafunction User Guide**



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## Introduction

As design complexities increase, the use of vendor-specific intellectual property (IP) blocks has become a common design methodology. Altera provides parameterizable megafunctions that are optimized for Altera® device architectures. Using megafunctions instead of coding your own logic saves valuable design time. Additionally, the Altera-provided functions offer more efficient logic synthesis and device implementation. You can scale the size of the megafunction by setting various parameters.

The advantage of floating-point numbers is that they can represent a much larger range of values. In a fixed-point number representation, the radix point is always at the same location. While the convention simplifies numeric operations and conserves memory, it places a limit on the magnitude and precision of the number representation. In situations that require a large range of numbers or high resolution, a relocatable radix point is desirable. Very large and very small numbers can be represented in a floating-point format.

Computing the inverse square root is necessary in many applications, such as vector normalization in video games.

## Features

The ALTFP\_INV\_SQRT megafunction calculates the inverse square root value of a given input. In addition, it offers the following features:

- Support for floating-point formats in single, double, and single-extended precision
- Input support for not-a-number (NaN), infinity, zero, and normal numbers
- Optional exception handling output ports such as `division_by_zero`, `nan`, and `zero`
- Optional input ports including asynchronous clear (`aclr`) and clock enable (`clk_en`)
- Support for round-to-nearest-even rounding mode

## General Description

The ALTFP\_INV\_SQRT megafunction follows the IEEE-754 standard for floating-point inverse and defines the following:

- The formats for representing floating-point numbers
- The representations of special values (zero, infinity, denormal numbers, and bit combinations that do not represent a number (NaN))

The IEEE-754 standard also defines four formats for floating-point numbers. The four formats are: single precision, double precision, single-extended precision, and double-extended precision. The most commonly used floating-point formats are single precision and double precision. The ALTFP\_INV\_SQRT megafunction only supports three formats: single precision, double precision, and single-extended precision.

All of the floating-point formats have binary patterns as shown in [Figure 1-1](#). In this figure:

- S represents a sign bit
- E represents an exponent field
- M is for the mantissa (part of a logarithm, or fraction) field

For a normal floating-point number, the leading 1 is always implied (for example, binary 1.0011 of decimal 1.1875 is stored as 0011 in the mantissa field). This format can save the mantissa field from using an extra bit to represent the leading 1. However, the leading bit for a denormal number can be either 0 or 1. For zero, infinity, and NaN, the mantissa field does not have a leading 1 implied or any explicit leading bit.

**Figure 1-1.** IEEE-754 Floating-Point Format



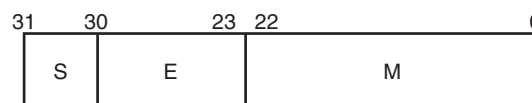
## Floating-Point Format

This section describes the formats for single precision, double precision, and single-extended precision.

### Single Precision

In single precision, the most significant bit is a sign bit, followed by 8 intermediate bits to represent an exponent, and 23 least significant bits (LSBs) to represent the mantissa. As a result, the total width for single precision is 32 bits. The bias for single precision is 127. Refer to [Figure 1-2](#).

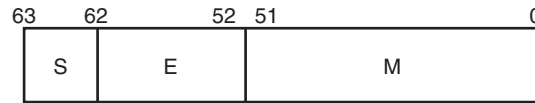
**Figure 1-2.** Single Precision Representation



## Double Precision

In double precision, the most significant bit is a sign bit, followed by 11 intermediate bits to represent an exponent, and 52 LSBs to represent the mantissa. As a result, the total width for double precision is 64 bits. The bias for double precision is 1023. Refer to [Figure 1-3](#).

**Figure 1-3.** Double Precision Representation



## Single-Extended Precision

In single-extended precision, the most significant bit (MSB) is a sign bit. However, the exponent and mantissa fields do not have fixed widths. The width of the exponent field must be a minimum of 11 bits and less than the width of the mantissa field. The width of the mantissa field must be a minimum of 31 bits. The sum of widths for the sign bit, exponent field, and mantissa field must be a minimum of 43 bits and a maximum of 64 bits. The bias for single-extended precision is unspecified in the IEEE-754 standard. In this megafunction, a bias of  $2^{(\text{WIDTH\_EXP}-1)}-1$  is assumed for single-extended precision.

## Special Case Numbers

[Table 1-1](#) shows the special case numbers defined by the IEEE-754 standard and the data bit representations.

**Table 1-1.** Special Case Numbers in IEEE-754 representation

Meaning	Sign Field	Exponent Field	Mantissa Field
Zero	Don't care	All 0's	All 0's
Positive Denormalized	0	All 0's	Non-zero
Negative Denormalized	1	All 0's	Non-zero
Positive Infinity	0	All 1's	All 0's
Negative Infinity	1	All 1's	All 0's
Not-a-Number (NaN)	Don't care	All 1's	Non-zero

## Rounding

In the IEEE-754 standard, there are four types of rounding modes: round-to-nearest-even, round-toward-zero, round-toward-positive-infinity, and round-toward-negative-infinity. The most commonly used rounding mode is round-to-nearest-even. This megafunction supports only round-to-nearest-even mode. With round-to-nearest-even, the result is rounded to the nearest floating-point number. If the result is exactly halfway between two floating-point numbers, it is rounded so that the LSB becomes a zero, which is even.

## Exception Handling

Three optional exception signals are provided: `division_by_zero`, `nan`, and `zero`. The `overflow` port is not available for this megafunction.

## Truth Table

Table 1-2 shows the truth table for the inverse square root operation.

**Table 1-2.** Truth Table for Inverse Square Root Operations

DATA[]	SIGN BIT	RESULT[]	Zero	Division_by_zero	NaN
Normal	0	Normal	0	0	0
Normal	1	NaN	0	0	1
Denormal (1)	0/1	Infinity	0	1	0
Zero	0/1	Infinity	0	1	0
Infinity	0/1	Zero	1	0	0
NaN	X	NaN	0	0	1

**Note to Table 1-2:**

(1) Any denormal input is treated as a zero before going through the Inverse Square Root process.

## Resource Utilization and Performance

Table 1-3 shows the resource utilization and performance information for the `ALTFP_INV_SQRT` megafunction.

**Table 1-3.** `ALTFP_INV_SQRT` Resource Usage and Performance for Stratix III devices (Note 1)

Precision	Output latency	Logic usage				f <sub>MAX</sub> (MHz)
		ALUTs	Registers	18-bit DSP	Memory	
Single	26	352	1,392	22	0	408.25
Double	36	1,093	3,878	78	0	200.31

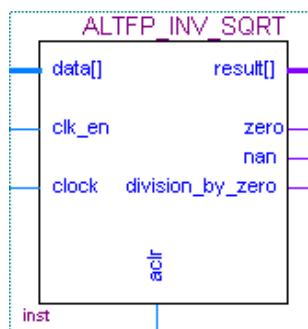
**Note to Table 1-3:**

(1) You can get the usage and performance information by compiling your design using the Quartus II software. The information in this table is valid and accurate in the Quartus II software version 8.1.

### MegaWizard Plug-In Manager Page Descriptions

Figure 2–1 shows the ports for the ALTFP\_INV\_SQRT megafunction.

**Figure 2–1.** Ports shown in the MegaWizard Plug-In Manager



Start the MegaWizard® Plug-In Manager in one of the following ways:

- On the Tools menu, click **MegaWizard Plug-In Manager**.
- When working in the Block Editor, from the Edit menu, click **Insert Symbol as Block**, or right-click in the Block Editor, point to **Insert**, and click **Symbol as Block**. In the Symbol window, click **MegaWizard Plug-In Manager**.
- Start the stand-alone version of the MegaWizard Plug-In Manager by typing the following command at the command prompt:

```
qmegawiz
```

The table below provides descriptions of the options available on the individual pages of the ALTFP\_INV\_SQRT MegaWizard Plug-In Manager.


**Table 2–1.** ALTFP\_INV\_SQRT MegaWizard Plug-In Manager Page Description (1 of 3)

MegaWizard Plug-in Manager Page	Configuration Setting	Description
1	Which action do you want to perform?	You can select from the following options: <b>Create a new custom megafunction variation</b> , <b>Edit an existing custom megafunction variation</b> , or <b>Copy an existing custom megafunction variation</b> .

**Table 2-1.** ALTFP\_INV\_SQRT MegaWizard Plug-In Manager Page Description (2 of 3)

<b>MegaWizard Plug-in Manager Page</b>	<b>Configuration Setting</b>	<b>Description</b>
2a	Select a megafunction from the list below	Select <b>ALTFP_INV_SQRT</b> from the <b>Arithmetic</b> category.
	Which device family will you be using?	Specify the device family that you want to use.
	Which type of output file do you want to create?	You can choose AHDL(. <b>tdf</b> ), VHDL(. <b>vhd</b> ), or Verilog HDL (. <b>v</b> ) as the output file type.
	What name do you want for the output file?	Specify the name of the output file.
	Return to this page for another create operation	Turn on this option if you want to return to this page to create multiple megafunctions.
3	Currently selected device family	Specifies the device family you chose on page 2a.
	Match project/default	Turn on this option to ensure that the device selected matches the device family that is chosen in the previous page.
	What is the floating-point format?	Select <b>Single precision</b> for 32 bits, <b>Double precision</b> for 64 bits, and <b>Single-extended precision</b> for 43 to 64 bits.
	What is the width of the 'data' input and 'result' output buses?	Specify the width of the buses. The maximum width is 32 bits for single precision, and 64 bits for double precision and single-extended precision.
	What is the width of the exponent port?	Specify the width of the exponent field. The maximum width is 30 bits.
	Mantissa width = (data width) - (exponent width) - 1	This option is not a user-specified option. The value is calculated automatically when the widths of the exponent field and input buses are specified.
	Output latency in clock cycles	Specify the latency for the result output in clock cycles. The value is fixed at 26 clock cycles for single precision and 36 clock cycles for double precision. For single-extended precision, the latency varies from 26 to 36 clock cycles.
4	Optional inputs	Two optional input ports are available: asynchronous clear port ( <b>aclr</b> ) and clock enable port ( <b>clk_en</b> ).
	Optional outputs	Three optional exception or output ports are available: <b>division_by_zero</b> , <b>nan</b> , and <b>zero</b> . The <b>overflow</b> port is disabled because it is not asserted under the Inverse Square Root operation.

**Table 2-1.** ALTFP\_INV\_SQRT MegaWizard Plug-In Manager Page Description (3 of 3)

MegaWizard Plug-in Manager Page	Configuration Setting	Description
5	Generate netlist	<p>Turn on this option if you want to generate a netlist for your third-party EDA synthesis tool to estimate the timing and resource usage of the megafunction. If you turn on this option, a netlist file (<b>_syn.v</b>) will be generated. This file is a representation of the customized logic used in the Quartus® II software and provides the connectivity of the architectural elements in the megafunction but may not represent true functionality.</p>
6	Summary Page	<p>Specify the types of files to be generated. The Variation file (<i>&lt;function name&gt;.v</i>) contains wrapper code in the language you specified on page 2a and is automatically generated. The Quartus II IP file (<i>&lt;function name&gt;.qip</i>) contains links to all the files required to compile an IP variation and is automatically generated when you add an IP core to a project. Choose from the following types of files:</p> <ul style="list-style-type: none"> <li>■ AHDL Include file (<i>&lt;function name&gt;.inc</i>)</li> <li>■ VHDL component declaration file (<i>&lt;function name&gt;.cmp</i>)</li> <li>■ Quartus II symbol file (<i>&lt;function name&gt;.bsf</i>)</li> <li>■ Instantiation template file (<i>&lt;function name&gt;_inst.v</i>)</li> <li>■ Verilog HDL black-box file (<i>&lt;function name&gt;_bb.v</i>)</li> </ul> <p> For more information about the wizard-generated files, refer to Quartus II Help or to the <i>Recommended HDL Coding Styles</i> chapter in volume 1 of the <i>Quartus II Handbook</i>.</p>

## Design Example: Inverse Square Root of Single Precision Numbers

This design example uses the ALTFP\_INV\_SQRT megafunction to compute the inverse square root value of single precision numbers. This example uses the MegaWizard Plug-In Manager in the Quartus II software.

### Design Files

The design files are available on the [Literature page](#) of the Altera website ([www.altera.com](http://www.altera.com)). They can be found under the following sections:

- On the [Quartus II Literature](#) page, expand the **Using Megafunctions** section and then expand the **Arithmetic** section
- [User Guides](#) section

### Example

Perform the following steps to compute the inverse square root value of single precision numbers:

1. Open `altfp_inv_sqrt_DesignExample.zip` and extract `fp_inv_sqrt_ex.qar`.
2. In the Quartus II software, open `fp_inv_sqrt_ex.qar` and restore the archive file into your working directory.
3. On the Tools menu, click **MegaWizard Plug-In Manager**. Page 1 of the MegaWizard Plug-In Manager appears.
4. Select **Create a new custom megafunction variation**.
5. Click **Next**. Page 2a of the MegaWizard Plug-In Manager appears.
6. In the MegaWizard Plug-In Manager pages, select or verify the configuration settings shown in [Table 2-2](#). Click **Next** to advance from one page to the next.

**Table 2-2.** Configuration Settings for ALTFP\_INV\_SQRT Design Example (1 of 2)

MegaWizard Plug-in Manager Page	Configuration Setting	Value
2a	Select a megafunction	ALTFP_INV_SQRT
	Which device family will you be using?	Stratix III
	Which type of output file do you want to create	Verilog HDL
	What name do you want for the output file?	fp_inv_sqrt_ex

**Table 2-2.** Configuration Settings for ALTFP\_INV\_SQRT Design Example (2 of 2)

MegaWizard Plug-in Manager Page	Configuration Setting	Value
3	Currently selected device family	Stratix III
	Match project/default	Selected
	What is the floating-point format?	Single precision (32 bits)
	What is the width of the 'data' input and 'result' output buses?	32 bits
	What is the width of the exponent port?	8 bits
	Mantissa width = (data width) - (exponent width) - 1	23 bits
	Output latency in clock cycles	26
4	Optional inputs	Select all
	Optional outputs	Select all
5	Generate netlist	Not selected
6	Variation file	Selected
	Quartus II IP file	Selected
	Quartus II symbol file	Not selected
	Instantiation template file	Not selected
	Verilog HDL black-box file	Selected
	AHDL Include file	Not selected
	VHDL component declaration file	Not selected

7. Click **Finish**.



If the **Quartus II IP Files** dialog box appears with an option to add the Quartus II IP file (.qip) to your project, click **Yes**.

The ALTFP\_INV\_SQRT module is now built.

## Functional Simulation in the ModelSim-Altera Software

Simulate the Floating-Point Inverse Square Root design in the ModelSim®-Altera software to generate a waveform display of the device behavior.

You should be familiar with the ModelSim-Altera software before trying out the design example. If you are unfamiliar with the ModelSim-Altera software, refer to the ModelSim support page on the Altera website ([www.altera.com](http://www.altera.com)). On this support page, there are links to such topics as installation, usage, and troubleshooting.

Set up and simulate the design in the ModelSim-Altera software by performing the following steps:

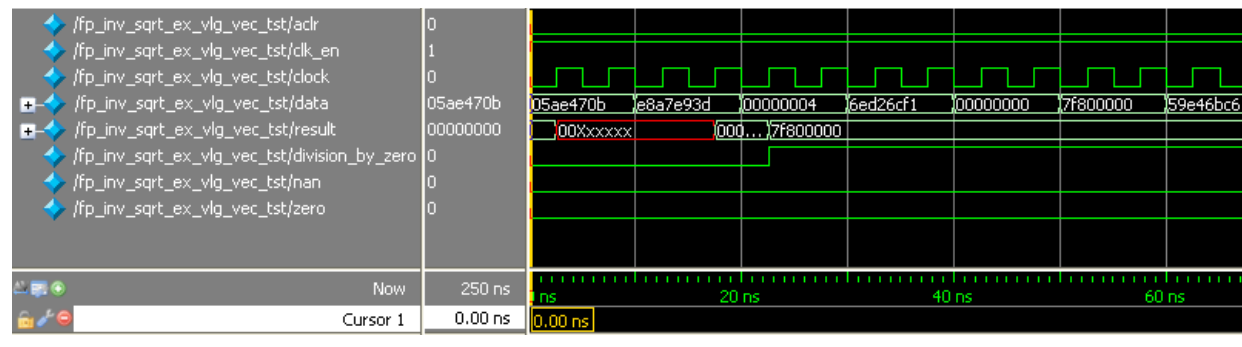
1. Unzip the **altfp\_inv\_sqrt\_ex\_msim.zip** file to any working directory on your PC.
2. Start the ModelSim-Altera software.
3. On the File menu, click **Change Directory**.

4. Select the folder in which you unzipped the files.
5. Click **OK**.
6. On the Tools menu, click **Execute Macro**.
7. Select the **fp\_inv\_sqrt\_ex.do** file and click **Open**. The **fp\_inv\_sqrt\_ex.do** file is a script file for the ModelSim-Altera software to automate all the necessary settings for the simulation.
8. Verify the results shown in the Waveform Viewer window.

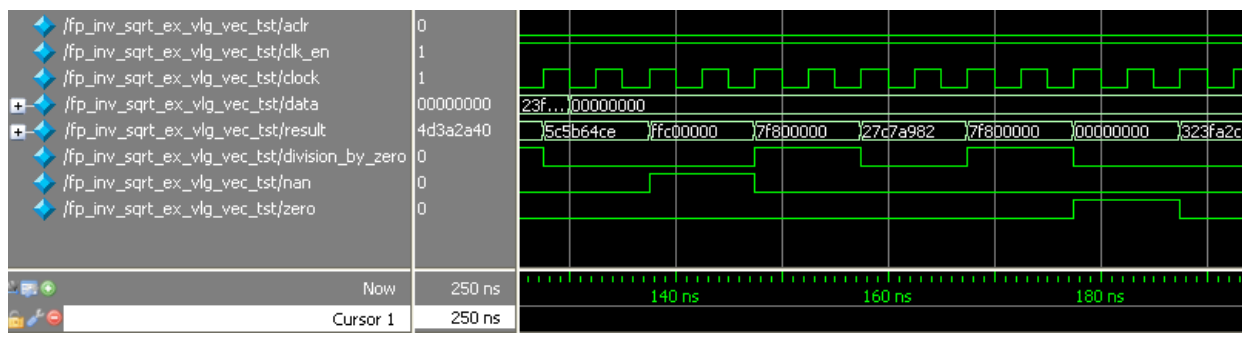
You can rearrange signals, remove signals, add signals, and change the radix by modifying the script in **fp\_inv\_sqrt\_ex.do** accordingly.

Figure 2-2 and Figure 2-3 show the expected simulation results in the ModelSim-Altera software.

**Figure 2-2.** ModelSim Simulation Waveforms (Input Data)



**Figure 2-3.** ModelSim Simulation Waveforms (Output Data)



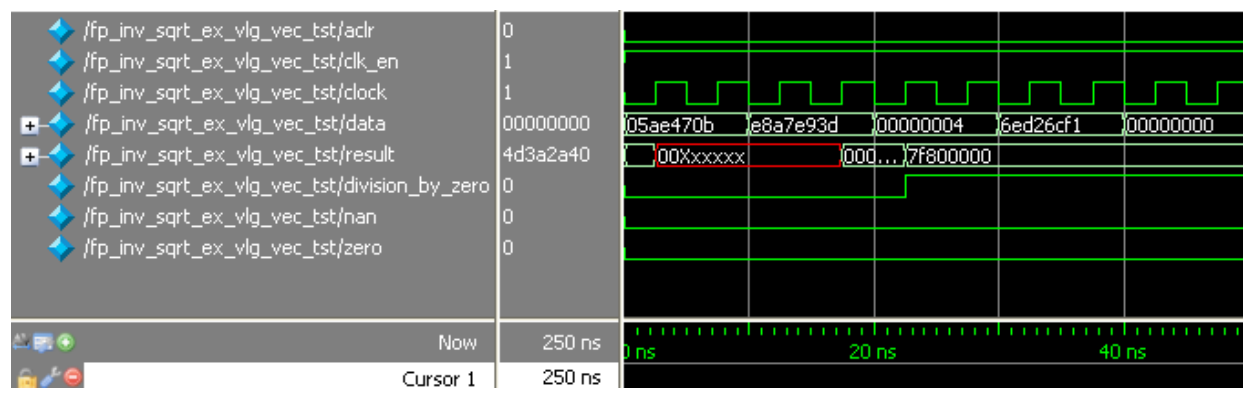
## Understanding the Simulation Results

The design example implements a floating-point inverse for single precision numbers. The optional input ports (`clk_en` and `aclr`) and all three exception handling output ports (`division_by_zero`, `nan`, and `zero`) are enabled.

The latency is fixed at 26 clock cycles; therefore every inverse square root operation outputs the results 26 clock cycles later.

An undefined value is present on the `result []` port during start-up. This undefined value is generated due to the behavior of the system. This value is insignificant and can be ignored. At 22.5 ns, the power-up values of the `data []` port are assumed to be zero, thus the `result []` port displays a value of 7F80000h, which represents infinity. This result is also obtained by assuming that the inversion values are all zeros, causing the `division_by_zero` port to be asserted. Refer to Figure 2-4.

Figure 2-4. Floating-Point Inverse Square Root at Power-Up



The result of the first input value is seen on the `result []` port 26 clock cycles after start-up. At 127.5 ns, the `division_by_zero` port deasserts, while 5C5B64CEh is seen on the `result []` port. The inverse square root of a normal number results in a normal value. Refer to Figure 2-5.

Figure 2-5. Inverse Square Root of a Normal Value Results in a Normal Value

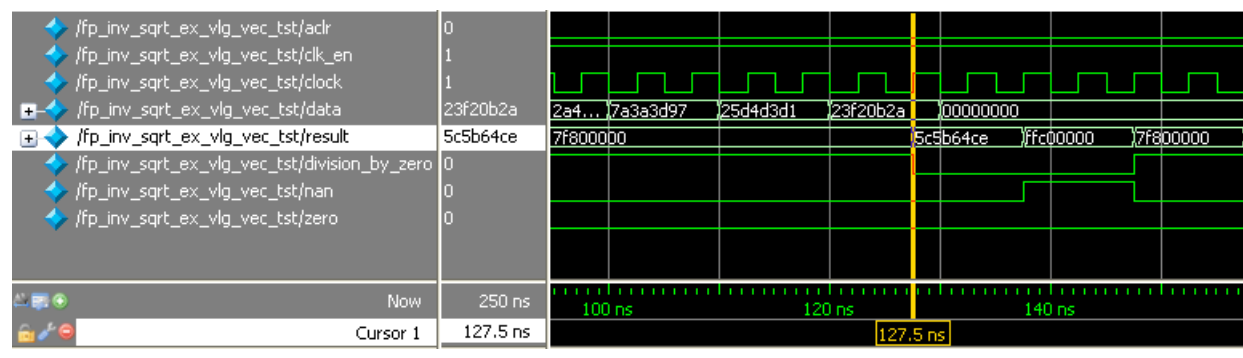
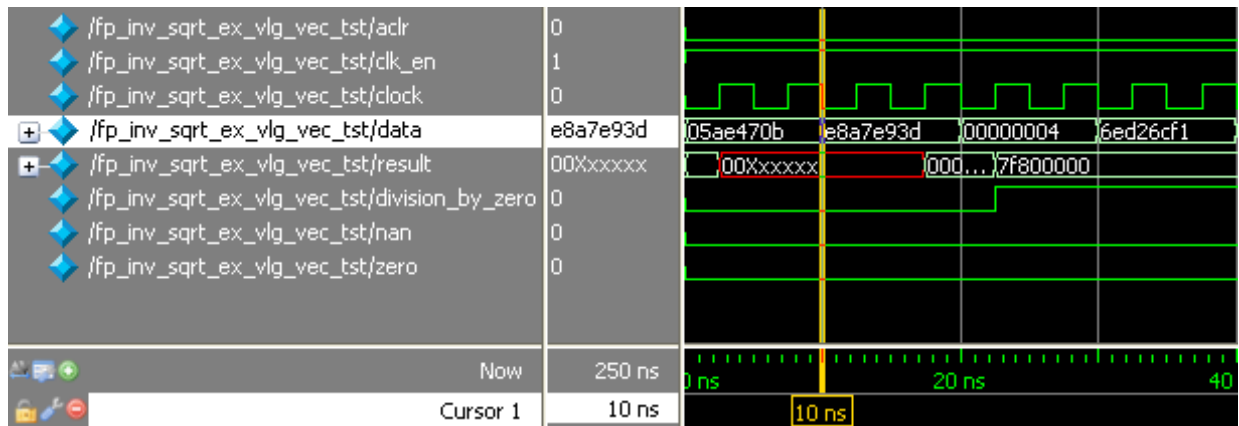


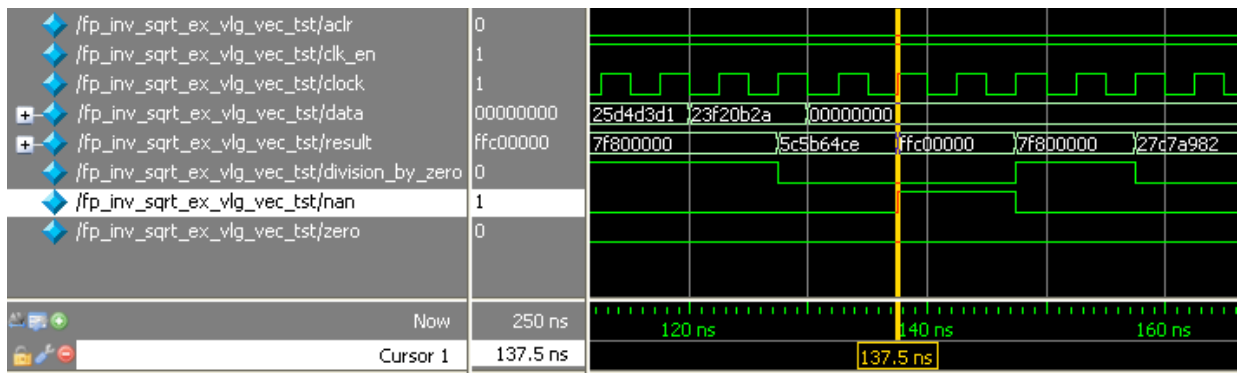
Figure 2-6 shows a negative normal value on the data [] port at 10 ns.

**Figure 2-6.** Floating-Point Input at 10 ns



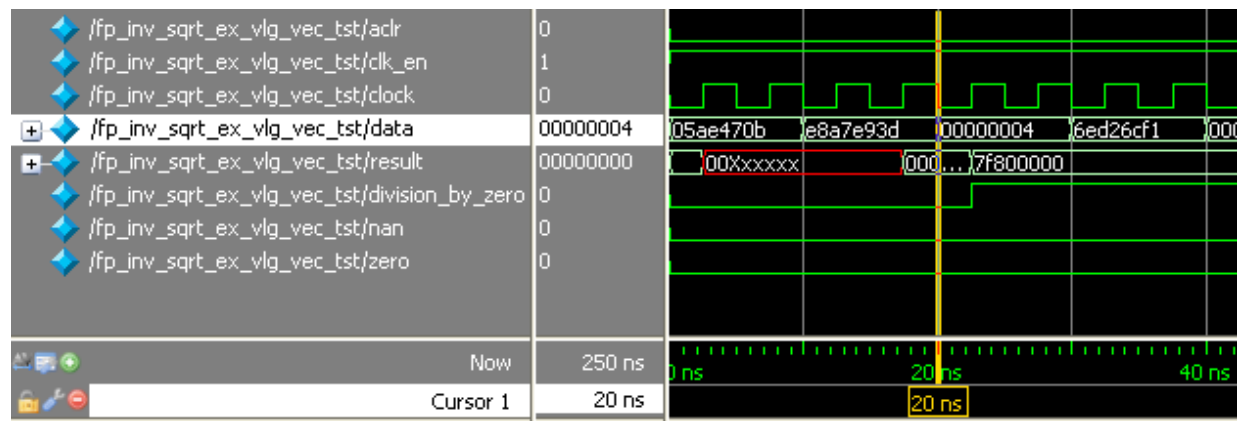
The outcome of the operation is seen on the result [] port at 137.5 ns. The inverse square root of a negative value produces a NaN (represented by FFC00000h), so the nan port is asserted. Refer to Figure 2-7.

**Figure 2-7.** Inverse Square Root of a Negative Value Results in a NaN



At 20 ns, a denormal value is seen on the data [] port. Refer to Figure 2-8.

**Figure 2-8.** Floating-Point Input at 20 ns



Denormal numbers are forced-zero values and the inverse square root of zero values results in a value of infinity. The previous nan port is deasserted and the division\_by\_zero port is asserted at 147.5 ns. Refer to Figure 2-9.

**Figure 2-9.** Inverse of a Denormal Value Results in Infinity

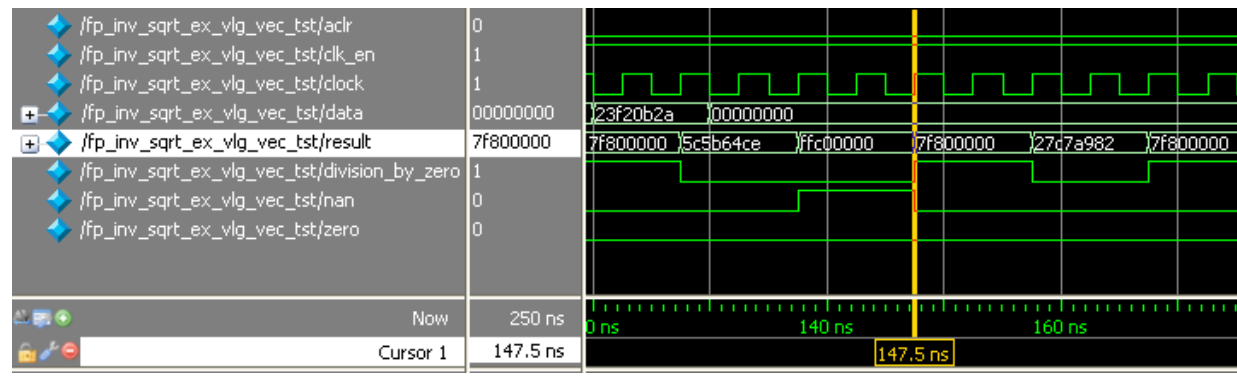
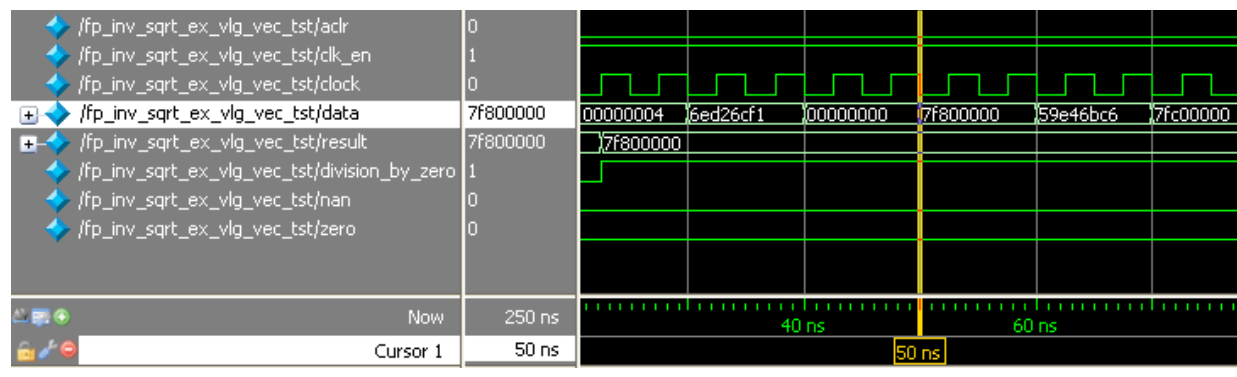


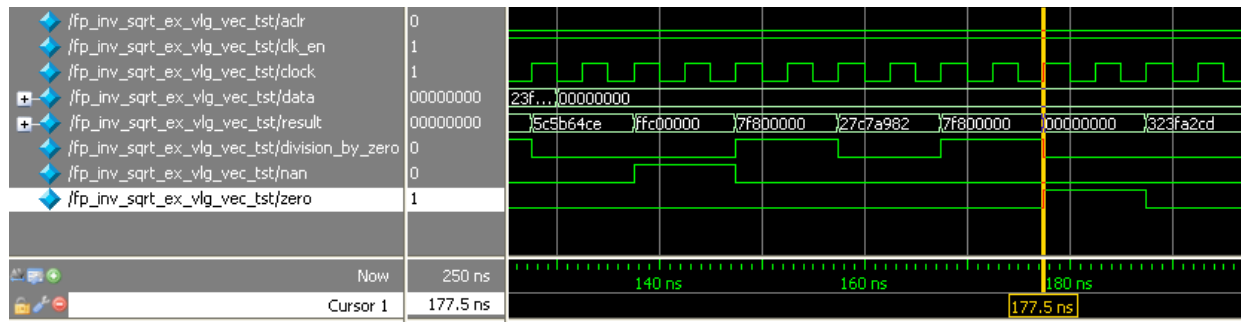
Figure 2-10 shows an infinity value on the data [] port at 50 ns.

**Figure 2-10.** Floating-Point Input at 50 ns



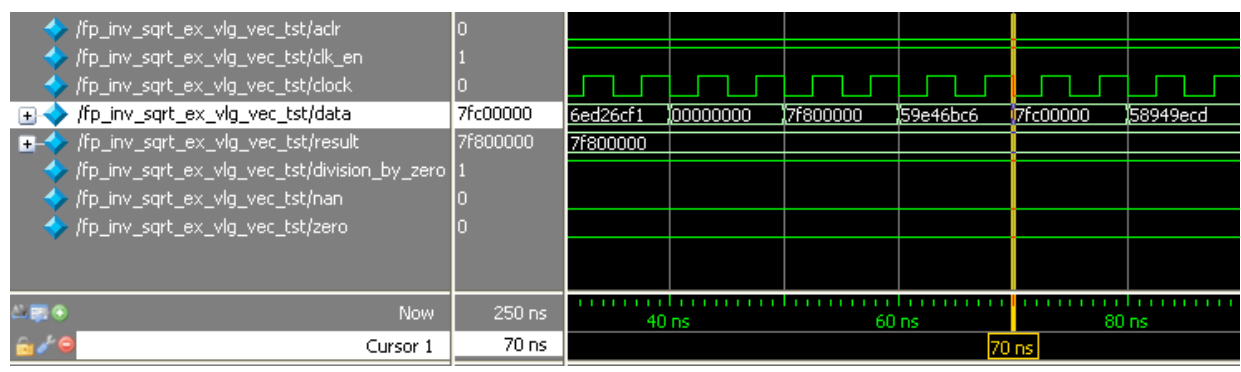
The outcome of the inverse square root operation is sent to the `result []` port at 177.5 ns. The inverse square root of an infinity value produces a zero, so the zero port is asserted. Refer to [Figure 2-11](#).

**Figure 2-11.** Inverse Square Root of an Infinity Value Results in Zero



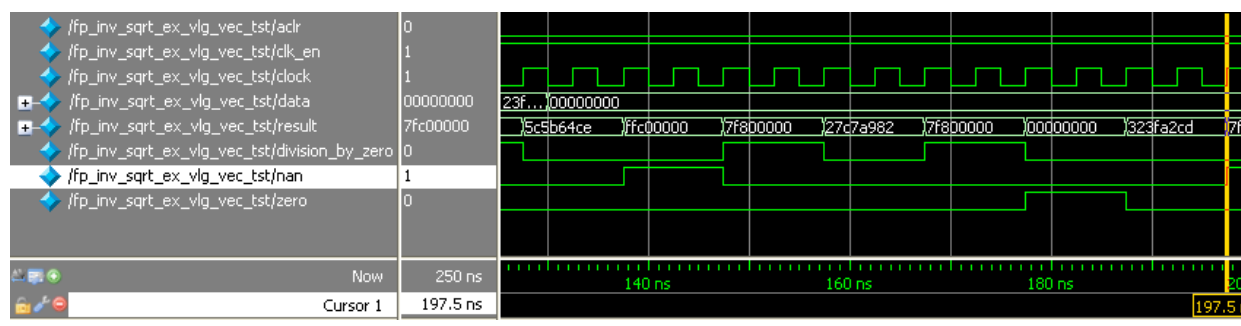
At 70 ns, the value on the `data []` port is a NaN. Refer to [Figure 2-12](#).

**Figure 2-12.** Floating-Point Input at 70 ns



[Figure 2-13](#) shows that the inverse square root of a NaN value results in another NaN value, so the `nan` port is asserted. The outcome of the inverse square root operation is seen at 197.5 ns.


**Figure 2-13.** Inverse Square Root of a NaN Results in a NaN



For more information about the floating-point inverse square root operation and the behavior of the output ports, refer to “[Table 1-2](#)” on [page 1-4](#).

## Ports and Parameters

The parameter details are only relevant for users who bypass the MegaWizard® Plug-In Manager interface and use the megafunction as a directly parameterized instantiation in their design. The details of these parameters are hidden from MegaWizard Plug-In Manager interface users.

 Refer to the latest version of the Quartus® II Help for the most current information about the ports and parameters of this megafunction.


 Altera strongly recommends that you use the MegaWizard Plug-In Manager for complex megafunctions. The MegaWizard Plug-In Manager ensures that you set all megafunction parameters properly.

Table 3–1 shows the input ports, Table 3–2 shows the output ports, and Table 3–3 shows the ALTFP\_INV\_SQRT megafunction parameters.

## Input Ports

**Table 3–1.** ALTFP\_INV\_SQRT Megafunction Input Ports

Port Name	Required	Description	Comments
<code>aclr</code>	No	Asynchronous clear	When the <code>aclr</code> port is asserted high the function is asynchronously cleared.
<code>clk_en</code>	No	Clock enable	When the <code>clk_en</code> port is asserted high, an inverse square root operation takes places. When this signal is asserted low, no operation occurs and the outputs remain unchanged.
<code>clock</code>	Yes	Clock input	The clock port is the clock input for ALTFP_INV_SQRT megafunction.
<code>data []</code>	Yes	Data input	Floating-point input data. The most significant bit (MSB) is the sign, the next most significant bits are the exponent, and the mantissa occupies the least significant bits. This input port size is the total width of sign bit, exponent bits and mantissa bits.

## Output Ports

**Table 3-2.** ALTFP\_INV\_SQRT Megafunction Output Ports

Port Name	Required	Description	Comments
<code>result []</code>	Yes	The floating-point inverse square root result of the input on <code>data []</code> .	The floating-point result. The MSB is the sign, the next most significant bits are the exponent, and the mantissa occupies the least significant bits. The size of this port is the total width of sign bit, exponent bits and mantissa bits.
<code>zero</code>	Yes	Zero value exception output.	Asserted when the value in the <code>result []</code> port is a zero.
<code>division_by_zero</code>	No	Division-by-zero exception output.	Asserted when the denominator input is a zero.
<code>nan</code>	Yes	Not-a-Number (NaN) exception output.	Asserted when an invalid inversion of square root occurs, such as the square root of a negative number. In this case, a <code>nan</code> value is output to the <code>result []</code> port. Any operation involving <code>nan</code> also asserts <code>nan</code> .

## Parameters

**Table 3-3.** ALTFP\_INV\_SQRT Megafunction Parameters

Parameter Name	Type	Required	Description
<code>WIDTH_EXP</code>	Integer	Yes	Specifies the precision of the exponent. If omitted, the default value for <code>WIDTH_EXP</code> is 8. The bias of the exponent is always set to $2^{(\text{WIDTH\_EXP}-1)}-1$ (for example, 127 for single precision floating-point format and 1023 for double precision floating-point format). The <code>WIDTH_EXP</code> value must be 8 for single precision floating-point format and 11 for double precision, and a minimum of 11 for single-extended precision. The <code>WIDTH_EXP</code> value must be less than the <code>WIDTH_MAN</code> value. The sum of <code>WIDTH_EXP</code> and <code>WIDTH_MAN</code> must be less than 64.
<code>WIDTH_MAN</code>	Integer	Yes	Specifies the precision of the mantissa. If omitted, the default value for <code>WIDTH_MAN</code> is 23. When the <code>WIDTH_EXP</code> value is 8 and the floating-point format is single precision, the <code>WIDTH_MAN</code> value must be 23. Otherwise, the value of <code>WIDTH_MAN</code> must be a minimum of 31. The <code>WIDTH_MAN</code> value must be greater than the <code>WIDTH_EXP</code> value. The sum of <code>WIDTH_EXP</code> and <code>WIDTH_MAN</code> must be less than 64.
<code>ROUNDING</code>	String	No	Specifies the rounding mode. The default value is <code>TO_NEAREST</code> . Other rounding modes are not supported.
<code>PIPELINE</code>	Integer	Yes	Specifies the amount of latency in clock cycles used in the ALTFP_INV_SQRT megafunction. Create the ALTFP_INV_SQRT megafunction variation with the MegaWizard Plug-In Manager to determine the value for this parameter.
<code>DEVICE_FAMILY</code>	String	Yes	This parameter is used for modeling and behavioral simulation purposes. Create the ALTFP_INV_SQRT megafunction variation with the MegaWizard Plug-In Manager to determine the value for this parameter.

## Document Revision History

The table below displays the revision history for the chapters in this User Guide.

Date	Document Version	Changes Made
November 2008	1.0	Initial release

## Referenced Documents

This user guide references the following documents:

- *Quartus II Integrated Synthesis* chapter in volume 1 of the *Quartus II Handbook*
- *Recommended HDL Coding Styles* chapter in volume 1 of the *Quartus II Handbook*
- *Simulation* section in volume 3 of the *Quartus II Handbook*
- *Synthesis* section in volume 1 of the *Quartus II Handbook*

## How to Contact Altera

For the most up-to-date information about Altera® products, refer to the following table.





Contact (1)	Contact Method	Address
Technical support	Website	<a href="http://www.altera.com/support">www.altera.com/support</a>
Technical training	Website	<a href="http://www.altera.com/training">www.altera.com/training</a>
	Email	<a href="mailto:custrain@altera.com">custrain@altera.com</a>
Product literature	Website	<a href="http://www.altera.com/literature">www.altera.com/literature</a>
Non-technical support (General) (Software Licensing)	Email	<a href="mailto:nacomp@altera.com">nacomp@altera.com</a>
	Email	<a href="mailto:authorization@altera.com">authorization@altera.com</a>

**Note to table:**

(1) You can also contact your local Altera sales office or sales representative.

# Typographic Conventions

This document uses the typographic conventions shown below.

Visual Cue	Meaning
<b>Bold Type with Initial Capital Letters</b>	Command names, dialog box titles, checkbox options, and dialog box options are shown in bold, initial capital letters. Example: <b>Save As</b> dialog box.
<b>bold type</b>	External timing parameters, directory names, project names, disk drive names, file names, file name extensions, and software utility names are shown in bold type. Examples: <b>f<sub>MAX</sub></b> , <b>\qdesigns</b> directory, <b>d:</b> drive, <b>chiptrip.gdf</b> file.
<i>Italic Type with Initial Capital Letters</i>	Document titles are shown in italic type with initial capital letters. Example: <i>AN 75: High-Speed Board Design.</i>
<i>Italic type</i>	Internal timing parameters and variables are shown in italic type. Examples: <i>t<sub>PIA</sub></i> , <i>n + 1</i> . Variable names are enclosed in angle brackets (< >) and shown in italic type. Example: < <i>file name</i> >, < <i>project name</i> >. <b>pdf</b> file.
Initial Capital Letters	Keyboard keys and menu names are shown with initial capital letters. Examples: Delete key, the Options menu.
"Subheading Title"	References to sections within a document and titles of on-line help topics are shown in quotation marks. Example: "Typographic Conventions."
Courier type	Signal and port names are shown in lowercase Courier type. Examples: data1, tdi, input. Active-low signals are denoted by suffix n, e.g., resetn. Anything that must be typed exactly as it appears is shown in Courier type. For example: c:\qdesigns\tutorial\chiptrip.gdf. Also, sections of an actual file, such as a Report File, references to parts of files (e.g., the AHDL keyword SUBDESIGN), as well as logic function names (e.g., TRI) are shown in Courier.
1., 2., 3., and a., b., c., etc.	Numbered steps are used in a list of items when the sequence of the items is important, such as the steps listed in a procedure.
■ ● •	Bullets are used in a list of items when the sequence of the items is not important.
✓	The checkmark indicates a procedure that consists of one step only.
	The hand points to information that requires special attention.
	A caution calls attention to a condition or possible situation that can damage or destroy the product or the user's work.
	A warning calls attention to a condition or possible situation that can cause injury to the user.
↵	The angled arrow indicates you should press the Enter key.
	The feet direct you to more information on a particular topic.